openPASS Steering Committee

**Meeting date**: 18 July 2025

**Location**: MS Teams

**Meeting minutes**: [Meeting Minutes · Wiki · Eclipse openpass · GitLab](https://gitlab.eclipse.org/groups/eclipse/openpass/-/wikis/Home/Meeting-Minutes)

**Participants**:

|  |  |  |
| --- | --- | --- |
| Name | Company | 2025-07-18 |
| Arun Das | BMW Group | X |
| Thomas Platzer | BMW Group | X |
| Katharina Donauer | BMW Group |  |
| Christopher Radinger | BMW Group |  |
| Michael Schwarzbach | BMW Group |  |
| Michael Plagge | Eclipse Foundation |  |
| Jan Dobberstein | Mercedes Benz AG on behalf of Mercedes-Benz Tech Innovation | X |
| Dr. Per Lewerenz | Mercedes Benz AG on behalf of Mercedes-Benz Tech Innovation | X |
| Dr. Daniel Schmidt | Robert Bosch GmbH |  |
| Dr. Stefan Schoenawa | Volkswagen AG | X |
| Dr. Gwendal Lucas | Volkswagen AG |  |

Minutes:

IP Review

* All: recap of discussion in AC on June 6 and July 4
* Jan: send reminder on two remaining tickets
* Arun: re-run requirements.txt file for opSimulation 🡺 correct issue for zlib will be created
* Arun: execute the requirements.txt file also for the other repositories (opGui and gt-gen)
	+ [requirements\_dash.txt · main · Jan Dobberstein / opGUI · GitLab](https://gitlab.eclipse.org/jdobberstein/opgui/-/blob/main/requirements_dash.txt)
	+ [requirements\_dash.txt · main · Jan Dobberstein / gt-gen-core · GitLab](https://gitlab.eclipse.org/jdobberstein/gt-gen-core/-/blob/main/requirements_dash.txt?ref_type=heads)
* After IP review is finished, commit process will include automatic check
	+ Developer guideline 🡺 link to IP clearance (“please update requirements.txt”)
	+ Commit: developer updates txt, if he uses new third party dependency
	+ MR on develop CI will check this txt file & IP lab ticket is created
	+ If ticket is closed 🡺 MR with new third party dependency can be merged

Gecco Updates:

* BMW: elastic collision postponed, plastic collision works
* Discussion: elastic collision needed for accident re-simulation (“PCM use case”)
* VW/MB: review collision detection / post collision dynamics in gecco